

FFI input to 2nd Seabed Characterization Workshop

January 10-11, 2012 • Dag Tollefsen (FFI Team)

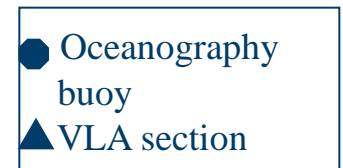
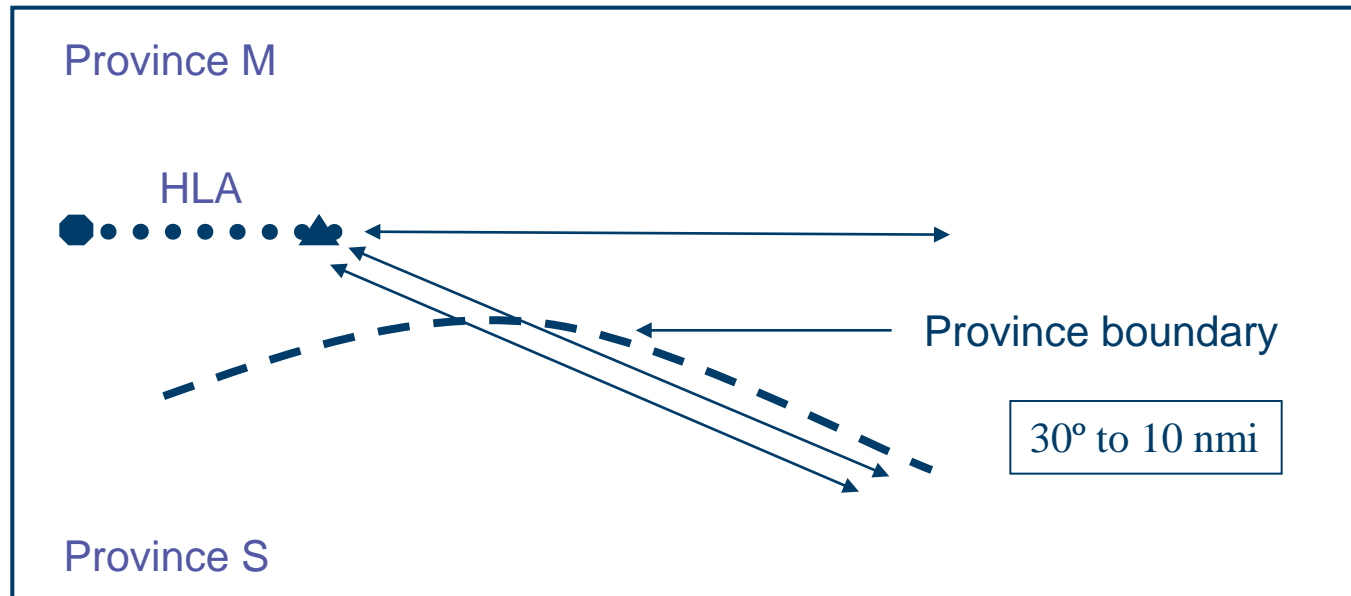
Research motivation:

1. Effects of variable seabed on long-range propagation
 - Range-dependent (cross-province) context
 - Side: thin geoacoustic layers (shear).
2. Quantify uncertainty → sonar predictions & array processing.
 - Account for oceanographic variability in inversions.

Participation:

1. Main experiment: FFI-array (and data analysis).
2. Side: smaller-scale Arctic Shelf initiative (FFI to facilitate).

Experiment

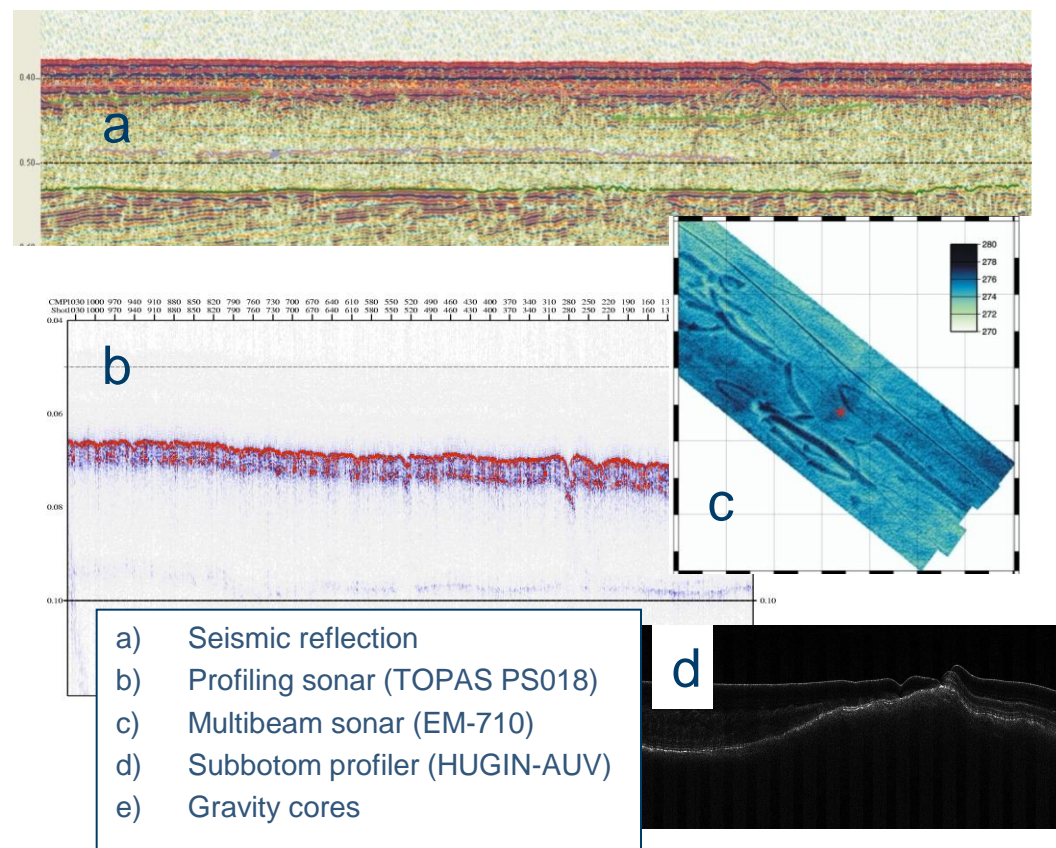


- Acoustic data:
 - Towed source (LF tones): EF & 30° to 10 nmi.
 - Repeated runs: sampling effects, model verification.
 - Short-range (broadband).
- Oceanographic: along-track & moored-buoy profiles.
- Geophysical: seismic profiler, cores, (shear).

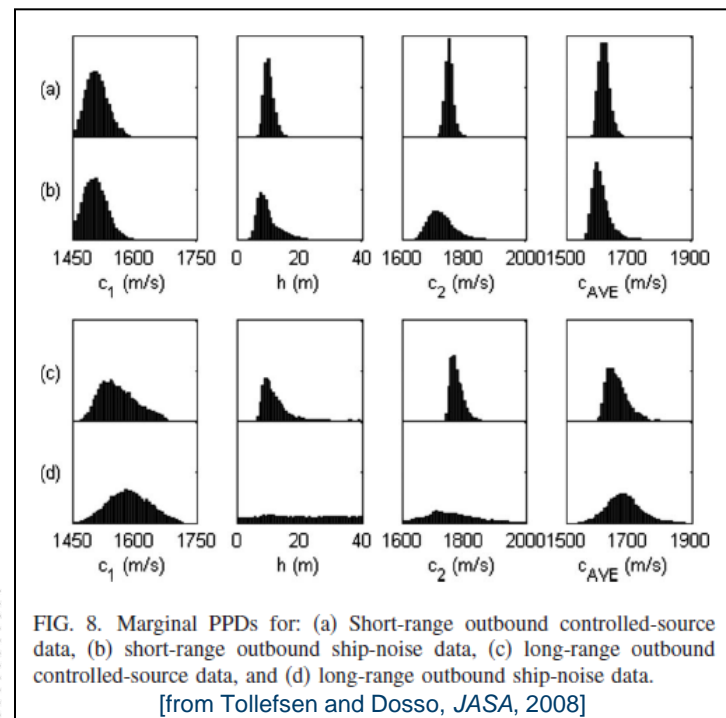
Prior & inferred information

Site survey

Bayesian inference

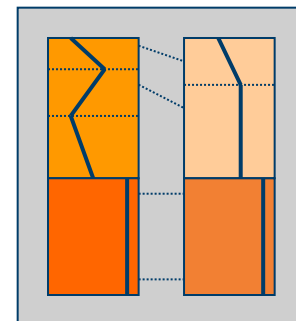


- a) Seismic reflection
- b) Profiling sonar (TOPAS PS018)
- c) Multibeam sonar (EM-710)
- d) Subbottom profiler (HUGIN-AUV)
- e) Gravity cores



Inference method

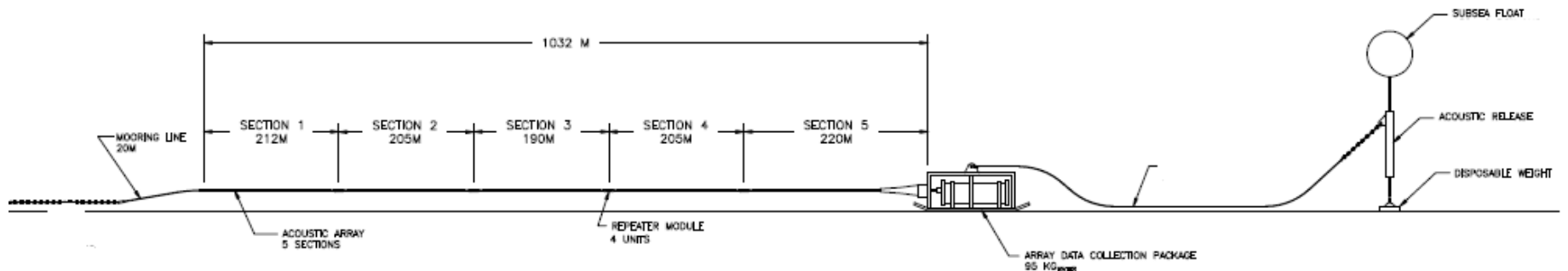
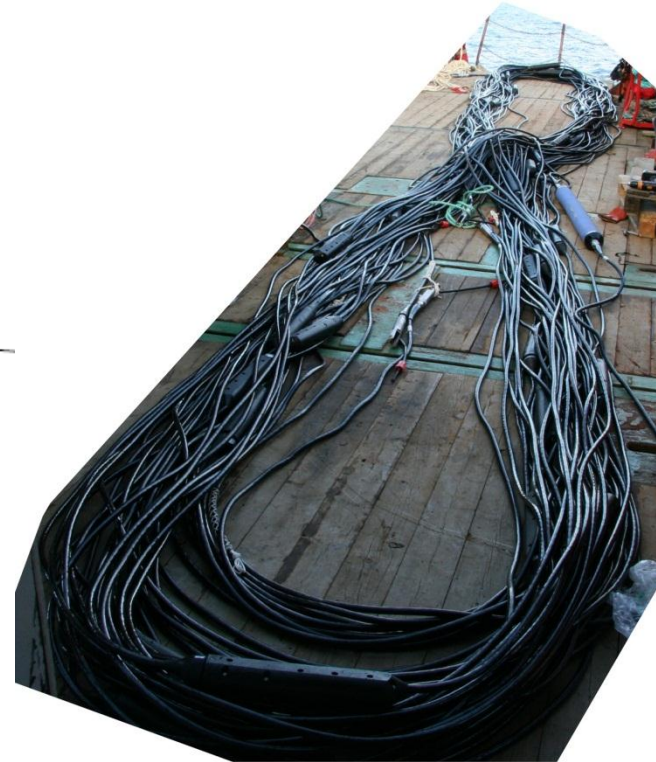
- Bayesian framework
 - Likelihood for Gaussian-distributed errors; data error C_d estimate, posterior analysis of residuals
 - Metropolis-Hastings sampling from PPD; heat-bath (Gibbs) sampling for source positions
 - Marginal posterior distributions and covariances.
- Model parameters:
 - N -layer (c, ρ, α) with gradients. Model selection via BIC.
 - extend to range-dependent context (segments).
 - variable oceanography via EOFs.
- Prior assumptions:
 - Wide (no-information) or narrow (prior-inversion) uniform bounds.
- Model parameter resolution: not assessed *a priori*.



FFI-array

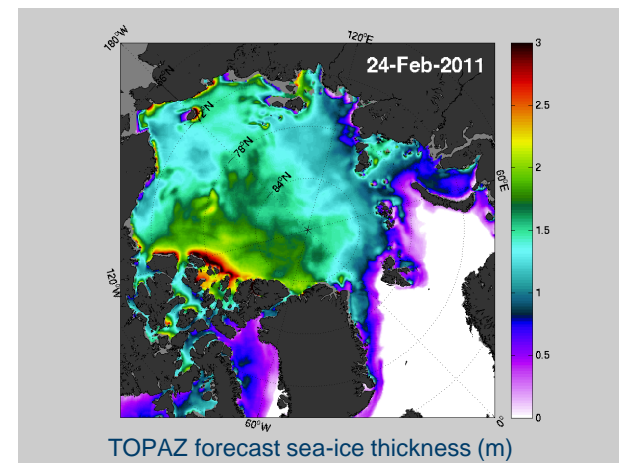
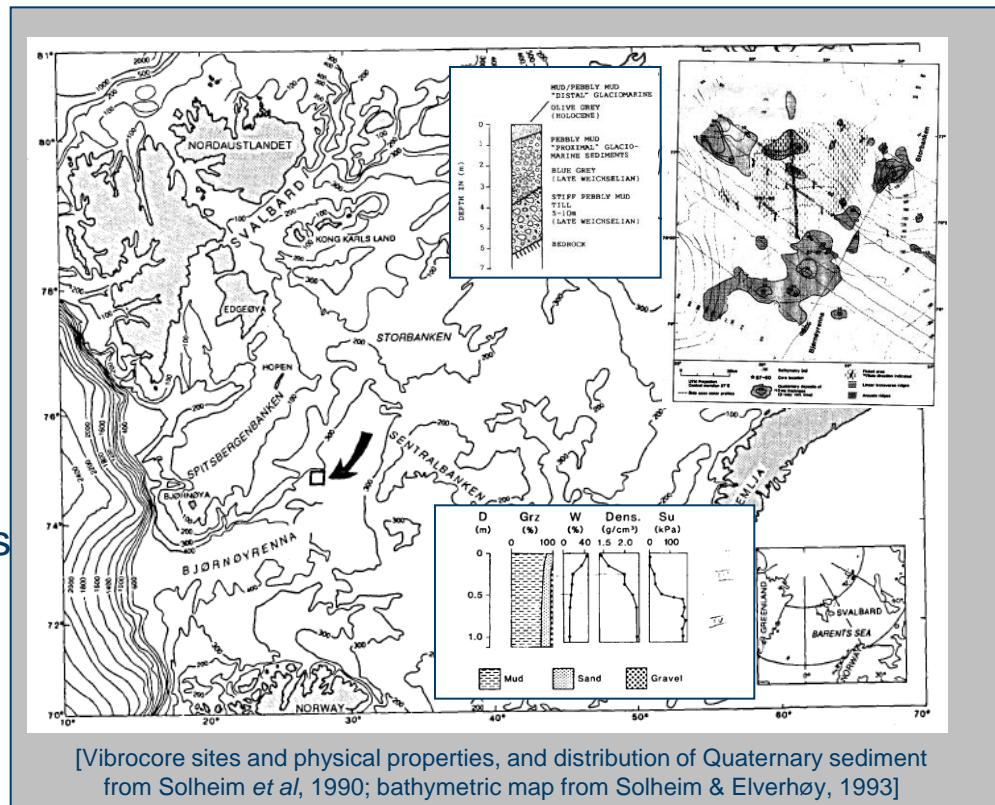
Specifications:

- Length 1032 m
- 63 hydrophones
- 10 Hz–2 kHz, 24-bit ADC
- 5 Tb memory
- 6 weeks endurance
- Depth rating 1000 m
- Acoustic link (status/control)
- Adjustable gain
- L-shape configuration TBD



Arctic Shelf

- Environmental data:
 - 50m to >400m depth
 - Bathy (mb) in general scarce
 - Legacy geoac data in select areas
 - Some additional seismic data.
- Ice conditions:
 - mid-Aug to mid-Sep window
 - yearly variations.
- Ship operations:
 - FFI Research Vessel (Ice cl. C)
 - Site survey
 - Combine with FFI-array expt.



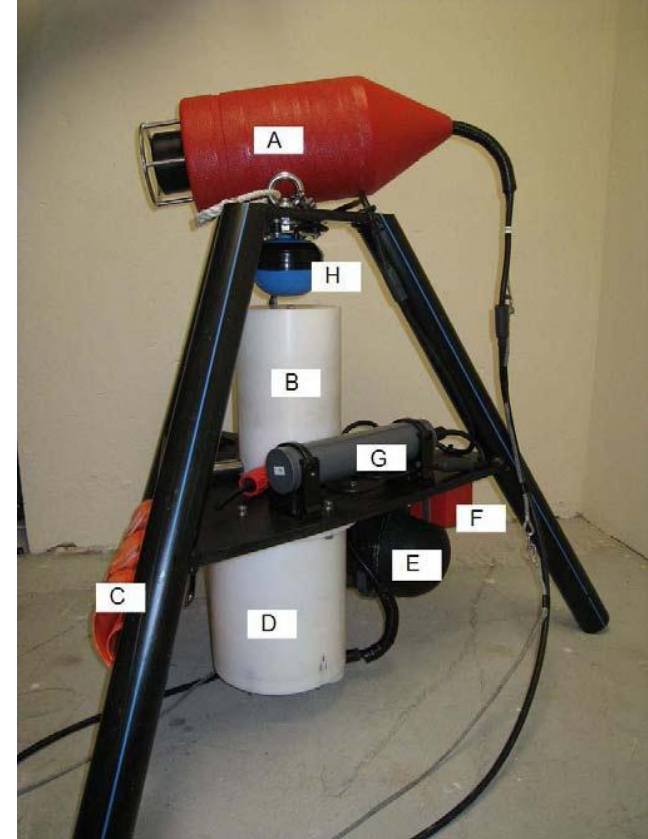
David's questions

- New about these measurements:
 - moving-source/fixed-array data in cross-province context (with high-resolution supporting information).
 - side: high-quality data set in Arctic Shelf environment.
- Latest expected technology:
 - state-of-the-art acoustic array (and Bayesian inference method).
- Collaboration:
 - Interactions with the SBCX team
 - Explore (informal) collaborations with ESL and UVic.

- EXTRA

NILUS bottom node

- Sensor nodes dropped onto the sea floor
- Modem in water column (increase range)
- Acoustic sensors:
 - DIFAR hydrophone or
 - 4 hydrophones in tetrahedron
30,3 cm between h/ps in plane;
top h/p 16,7 cm above centre
- Magnetic sensor (3-axial fluxgate)
- Local signal processing
 - Atmel AP7000 processor
- Tripod structure
- Flotation bag for easy recovery
- 10-day battery endurance (per 2011).



R/V H U SVERDRUP II

- 55-m length overall, 13m breadth, 5.5m draft, 1387GRT,
- Approx. 200 m² deck space, 10-ton A-frame, 3-ton crane, trawl winch, side winch, 150 m² wet and electronics labs.
- Echosounders: EA-600 SB, EM-710 MB, PS018 bottom profiling.
- HUGIN-1000 AUV; deck container, aft launch.
- 2x40 cu. in. airgun, Moving Vessel Profiler, ADCP.
- Berths for 15 scientists, 7 crew.
- Operates 11 months/yr, mainly mapping and survey tasks, external hire.



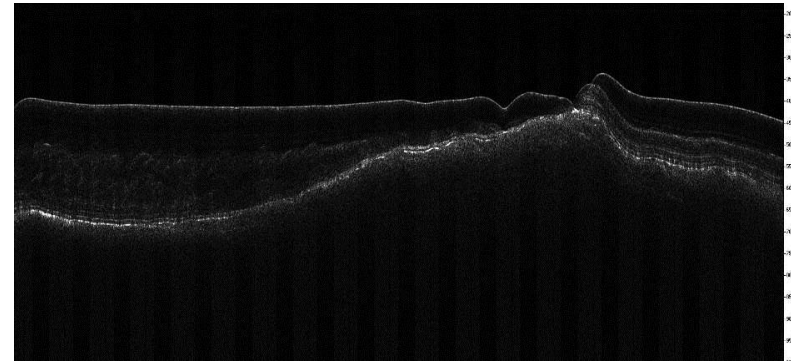
HUGIN 1000



1000 m depth rating, mobilization container,
L:4.5m, ϕ 75cm, sp:2-6 kts, 24 hrs@4 kts.

Equipment (April 2011)

- Multibeam – KM EM2000 (200 kHz)
- Singlebeam – KM (300 kHz)
- Sidescan – EdgeTech 2200 (120 & 410 kHz)
- KM-HISAS-1030 (60-120 kHz)
- Subbottom Profiler – EdgeTech (2–16 kHz)
- Forward looking – BlueView (200 kHz)
- Oceanographic – FSI Micro CTD 2
- Methane sniffer – Contros HydroC
- ADCP, Optical camera, Navigation sensors.



SBP – example (630m depth, 35 m height)